

```
ics
(depth < MAXDEPTH)
inside ? 1 : 0;
nt = nt / nc; ddn = ddn * ddn;
s2t = 1.0f - nnt * nnt;
D, N );
)
at a = nt - nc, b = nt * nc;
at Tr = 1 - (R0 + (1 - R0) * s2t);
Fr) R = (D * nnt - N * (ddn *
E * diffuse;
= true;
efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;
MAXDEPTH)
survive = SurvivalProbability( diffuse, i);
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light);
e.x + radiance.y + radiance.z) > 0) && (abs(radiance
w = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance
random walk - done properly, closely following
ive)
;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf);
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
```

/INFOMOV/

Optimization & Vectorization

J. Bikker - April - June 2024 - Lecture 7: "SIMD (2)"

Welcome!



Today's Agenda:

- Recap
- Flow Control
- AVX, Larrabee, GPGPU

```
ics
& (depth < MAXDEPTH)
{
    if ( ! inside )
    {
        nt = nt / nc; ddn = ddn * ddn;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
    at a = nt - nc; b = nt * nc;
    at Tr = 1 - (R0 + (1 - R0) *
    Tr) R = (D * nnt - N * (ddn *
    E * diffuse;
    = true;
    -
    refl + refr)) && (depth < MAXDEPTH)
    D, N );
    refl * E * diffuse;
    = true;
    MAXDEPTH)
    survive = SurvivalProbability( diffuse );
    estimation - doing it properly, closely following
    if;
    radiance = SampleLight( &rand, I, &L, &light;
    e.x + radiance.y + radiance.z) > 0) && (abs(
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance
    random walk - done properly, closely following
    survive)
    ;
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf;
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;
}
```



Recap

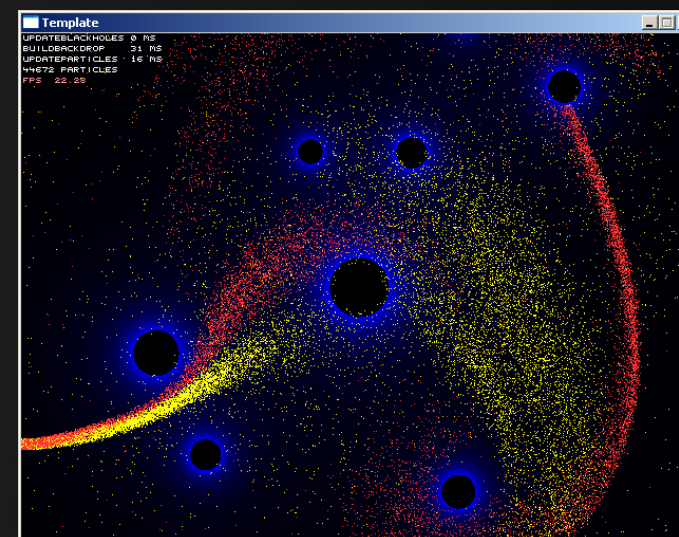
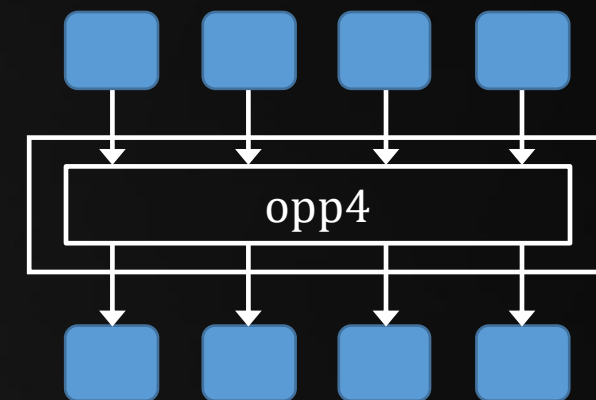
SSE: Four Floats

```

union
{
    __m128 a4;
    float a[4];
};

a4 = _mm_sub_ps( va11, va12 );
float sum = a[0] + a[1] + a[2] + a[3];

__m128 b4 = _mm_sqrt_ps( a4 );
__m128 m4 = _mm_max_ps( a4, b4 );
    
```



Recap

SSE: Four Floats

```

ics
& (depth < MAXDEPTH)
c = inside ? 1.0f : 0.0f;
nt = nt / nc; ddn = ddn * ddn;
ps2t = 1.0f - nnt * nnt;
D, N );
0);
at a = nt - nc, b = nt * nc;
at Tr = 1 - (R0 + (1 - R0) * c);
R = (D * nnt - N * (ddn *
E * diffuse;
= true;
efl + refr) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;
MAXDEPTH)
survive = SurvivalProbability( diffuse,
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light,
e.x + radiance.y + radiance.z) > 0) && (depth <
v = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance
random walk - done properly, closely following
ive)
;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf;
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;

```

`_mm_add_ps`
`_mm_sub_ps`
`_mm_mul_ps`
`_mm_div_ps`

`_mm_sqrt_ps`
`_mm_rcp_ps`
`_mm_rsqrt_ps`

`_mm_add_epi32`
`_mm_sub_epi32`
~~`_mm_mul_epi32`~~
~~`_mm_div_epi32`~~

~~`_mm_sqrt_epi32`~~
~~`_mm_rcp_epi32`~~
~~`_mm_rsqrt_epi32`~~

`_mm_cvtps_epi32`
`_mm_cvtepi32_ps`

`_mm_slli_epi32`
`_mm_srai_epi32`

`_mm_cmpeq_epi32`

`_mm_add_epi16`
`_mm_sub_epi16`

`_mm_add_epu8`
`_mm_sub_epu8`

`_mm_mul_epu32`

`_mm_add_epi64`
`_mm_sub_epi64`

Actually...
`_mm_mul_epi32` *does* exist. However, it produces 2 64-bit numbers, not 4 32-bit numbers.

Actually...
 Intel’s ‘short vector math lib’ (SVML) has the `_mm_div_epi32` instruction. However, as they note:

1. It’s a ‘sequence of instructions’;
2. “Many routines in the SVML are ‘more optimized’ for Intel CPUs.”
(read: are deliberately crippled for AMD)



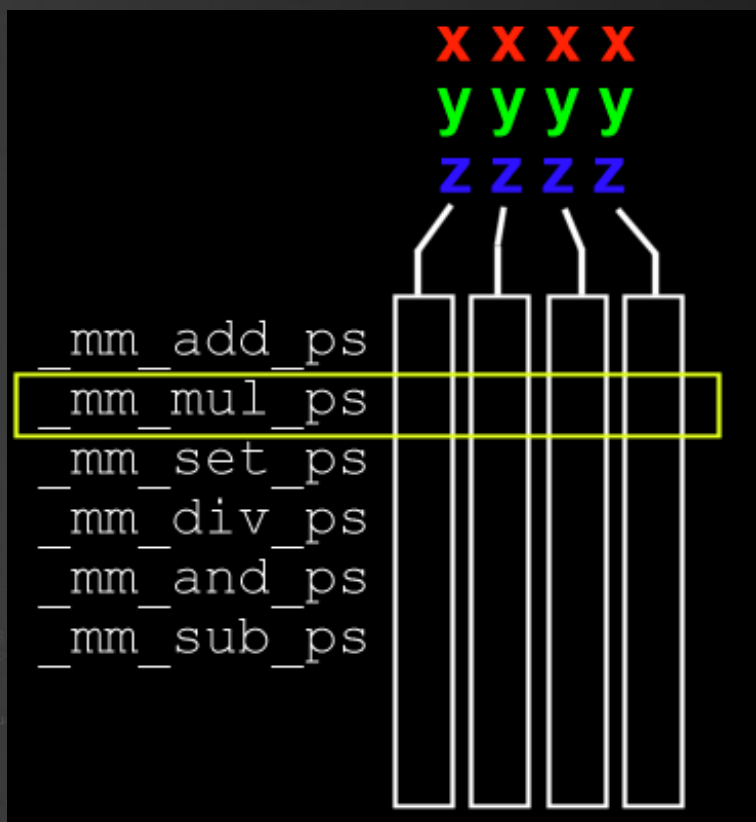
Recap

SSE: Four Floats

```

...ics
& (depth < MAXDEPTH)
...
c = inside ? 1.0f : 0.0f;
nt = nt / nc; ddn = sqrt(1 - c);
cos2t = 1.0f - nnt * ddn;
D, N );
0);
...
at a = nt - nc, b = nt * nc;
at Tr = 1 - (R0 + (1 - R0) * ddn);
Tr) R = (D * nnt - N * (ddn * ddn));
...
E * diffuse;
= true;
...
efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;
...
MAXDEPTH)
survive = SurvivalProbability( diffuse, r,
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, Alig
e.x + radiance.y + radiance.z) > 0) && (co
...
v = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psu
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf)
...
random walk - done properly, closely following
survive)
...
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, Spdf
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;

```



AOS

SOA

structure
of
arrays



Recap

SSE: Four Floats

```
struct Particle
{
    float x, y, z;
    int mass;
};
Particle particle[512];
```

AOS

```
union { float x[512]; __m128 x4[128]; };
union { float y[512]; __m128 y4[128]; };
union { float z[512]; __m128 z4[128]; };
union { int mass[512]; __m128i mass4[128]; };
```

SOA

structure of arrays



Recap

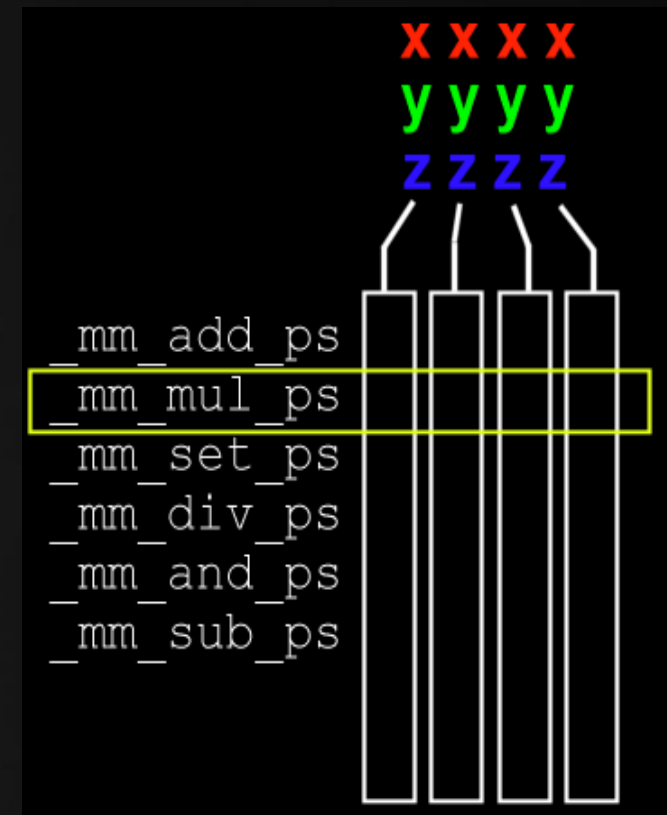
Vectorization:

“The Art of rewriting your algorithm so that it operates in four separate streams, rather than one.”

Note: compilers will apply SSE2/3/4 for you as well:

```
vector3f A = { 0, 1, 2 };
vector3f B = { 5, 5, 5 };
A += B;
```

This will marginally speed up *one line* of your code; manual vectorization is fundamental and requires data reordering.

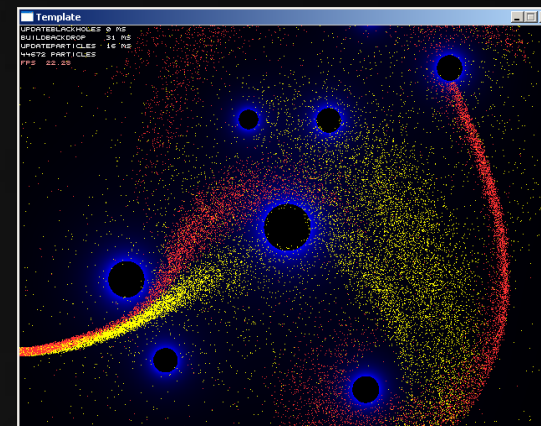


Recap

```

void Game::BuildBackdrop()
{
    Pixel* dst = m_Surface->GetBuffer();
    float fy = 0;
    for ( unsigned int y = 0; y < SCRHEIGHT; y++, fy++ )
    {
        float fx = 0;
        for ( unsigned int x = 0; x < SCRWIDTH; x++, fx++ )
        {
            float g = 0;
            for ( unsigned int i = 0; i < HOLES; i++ )
            {
                float dx = m_Hole[i]->x - fx, dy = m_Hole[i]->y - fy;
                float squareddist = ( dx * dx + dy * dy );
                g += (250.0f * m_Hole[i]->g) / squareddist;
            }
            if (g > 1) g = 0;
            *dst++ = (int)(g * 255.0f);
        }
        dst += m_Surface->GetPitch() - m_Surface->GetWidth();
    }
}

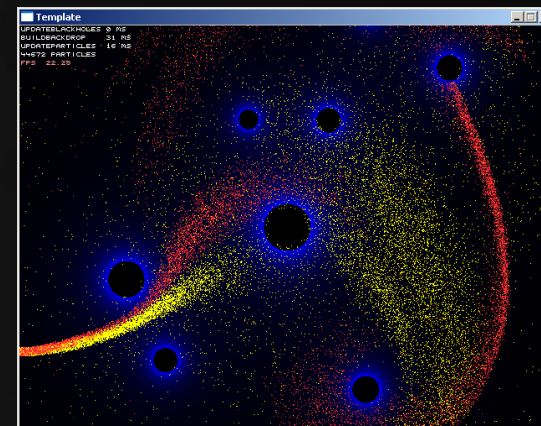
```



Recap

```

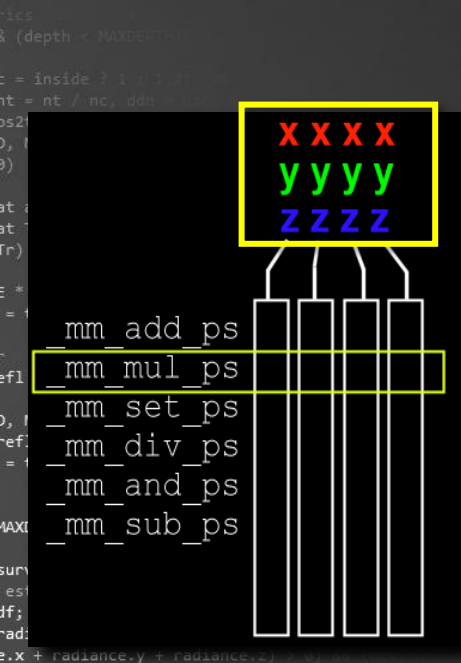
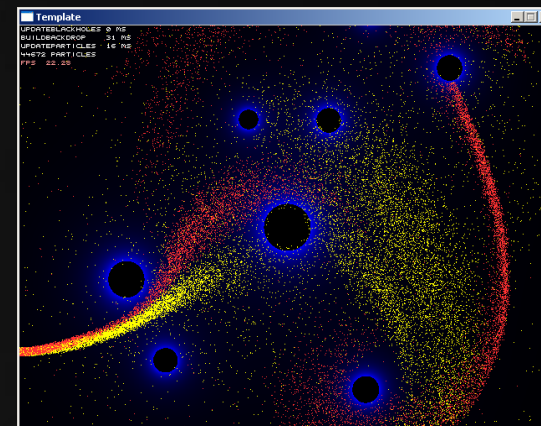
void Game::BuildBackdrop()
{
    Pixel* dst = m_Surface->GetBuffer();
    float fy = 0;
    for ( unsigned int y = 0; y < SCRHEIGHT; y++, fy++ )
    {
        float fx = 0;
        for ( unsigned int x = 0; x < SCRWIDTH; x++, fx++ )
        {
            float g = 0;
            for ( unsigned int i = 0; i < HOLES / 4; i++ )
            {
                float dx = m_Hole[i]->x - fx, dy = m_Hole[i]->y - fy;
                float squareddist = ( dx * dx + dy * dy );
                g += (250.0f * m_Hole[i]->g) / squareddist;
            }
            if (g > 1) g = 0;
            *dst++ = (int)(g * 255.0f);
        }
        dst += m_Surface->GetPitch() - m_Surface->GetWidth();
    }
}
    
```



Recap

```

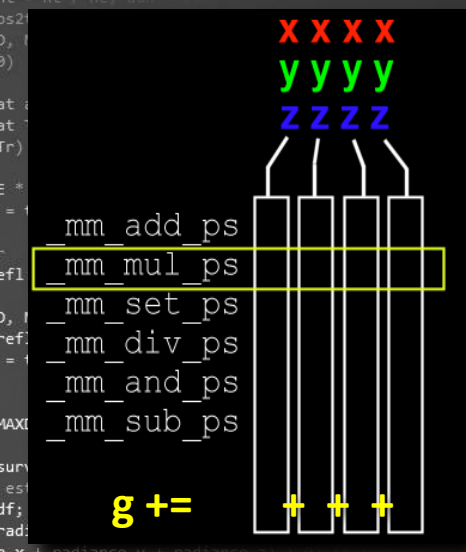
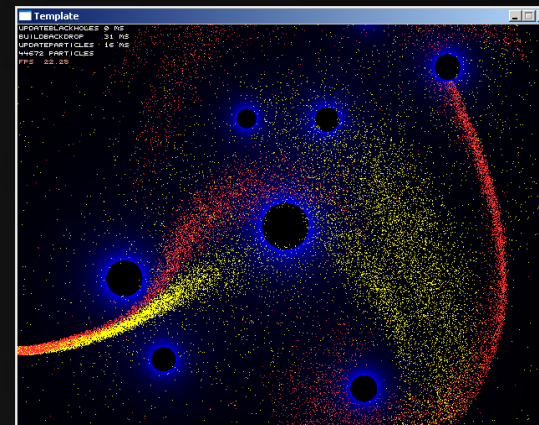
void Game::BuildBackdrop()
{
    Pixel* dst = m_Surface->GetBuffer();
    float fy = 0;
    for ( unsigned int y = 0; y < SCRHEIGHT; y++, fy++ )
    {
        float fx = 0;
        for ( unsigned int x = 0; x < SCRWIDTH; x++, fx++ )
        {
            float g = 0;
            __m128 g4 = _mm_setzero_ps();
            for ( unsigned int i = 0; i < HOLES / 4; i++ )
            {
                __m128 dx4 = _mm_sub_ps( bhx4[i], fx4 );
                __m128 dy4 = _mm_sub_ps( bhy4[i], fy4 );
                __m128 sq4 = _mm_add_ps( _mm_mul_ps( dx4, dx4 ), _mm_mul_ps( dy4, dy4 ) );
                __m128 mulresult4 = _mm_mul_ps( _mm_set1_ps( 250.0f ), bhg4[i] );
                g4 = _mm_add_ps( g4, _mm_div_ps( mulresult4, sq4 ) );
            }
            if ( g > 1) g = 0;
            *dst++ = (int)(g * 255.0f);
        }
        dst += m_Surface->GetPitch() - m_Surface->GetWidth();
    }
}
    
```



Recap

```

void Game::BuildBackdrop()
{
    Pixel* dst = m_Surface->GetBuffer();
    float fy = 0;
    for ( unsigned int y = 0; y < SCRHEIGHT; y++, fy++ )
    {
        float fx = 0;
        for ( unsigned int x = 0; x < SCRWIDTH; x++, fx++ )
        {
            float g = 0; __m128 g4 = __mm_setzero_ps();
            for ( unsigned int i = 0; i < HOLES / 4; i++ )
            {
                __m128 dx4 = __mm_sub_ps( bhx4[i], fx4 );
                __m128 dy4 = __mm_sub_ps( bhy4[i], fy4 );
                __m128 sq4 = __mm_add_ps( __mm_mul_ps( dx4, dx4 ), __mm_mul_ps( dy4, dy4 ) );
                __m128 mulresult4 = __mm_mul_ps( __mm_set1_ps( 250.0f ), bhg4[i] );
                g4 = __mm_add_ps( g4, __mm_div_ps( mulresult4, sq4 ) );
            }
            g += g_[0] + g_[1] + g_[2] + g_[3];
            if ( g > 1) g = 0;
            *dst++ = (int)(g * 255.0f);
        }
        dst += m_Surface->GetPitch() - m_Surface->GetWidth();
    }
}
    
```



g += g_[0] + g_[1] + g_[2] + g_[3];

“Horizontal operation”



Today's Agenda:

- Recap
- Flow Control
- AVX, Larrabee, GPGPU

```
ics
& (depth < MAXDEPTH)
{
    if ( ! inside )
    {
        nt = nt / nc; ddn = ddn * ddn;
        cos2t = 1.0f - nnt * nnt;
        D, N );
    }
    at a = nt - nc; b = nt + nc;
    at Tr = 1 - (R0 + (1 - R0) * r);
    Tr) R = (D * nnt - N * (ddn *
    E * diffuse;
    = true;
    -
    refl + refr)) && (depth < MAXDEPTH)
    D, N );
    refl * E * diffuse;
    = true;
    MAXDEPTH)
    survive = SurvivalProbability( diffuse );
    estimation - doing it properly, closely following
    if;
    radiance = SampleLight( &rand, I, &L, &align,
    e.x + radiance.y + radiance.z) > 0) && (abs(
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance
    random walk - done properly, closely following
    survive)
    ;
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf );
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;
}
```



Flow

```

for ( uint i = 0; i < PARTICLES; i++ ) if ( m_Particle[i]->alive)
{
    m_Particle[i]->x += m_Particle[i]->vx;
    m_Particle[i]->y += m_Particle[i]->vy;
    if (!( (m_Particle[i]->x < (2 * SCRWIDTH)) && (m_Particle[i]->x > -SCRWIDTH) &&
          (m_Particle[i]->y < (2 * SCRHEIGHT)) && (m_Particle[i]->y > -SCRHEIGHT)))
    {
        SpawnParticle( i );
        continue;
    }
    for ( uint h = 0; h < HOLES; h++ )
    {
        float dx = m_Hole[h]->x - m_Particle[i]->x;
        float dy = m_Hole[h]->y - m_Particle[i]->y;
        float sd = dx * dx + dy * dy;
        float dist = 1.0f / sqrtf( sd );
        dx *= dist, dy *= dist;
        float g = (250.0f * m_Hole[h]->g * m_Particle[i]->m) / sd;
        if (g >= 1) { SpawnParticle( i ); break; }
        m_Particle[i]->vx += 0.5f * g * dx;
        m_Particle[i]->vy += 0.5f * g * dy;
    }
    int x = (int)m_Particle[i]->x, y = (int)m_Particle[i]->y;
    if ((x >= 0) && (x < SCRWIDTH) && (y >= 0) && (y < SCRHEIGHT))
        m_Surface->GetBuffer()[x + y * m_Surface->GetPitch()] = m_Particle[i]->c;
}

```



Flow Control

Broken Streams

FALSE == 0, TRUE == 1:

Masking allows us to run code unconditionally, without consequences.

```

ics
& (depth < MAXDEPTH)
{
    if ( !inside ) {
        nt = nt / nc; ddn = ddn * nc;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
    at a = nt - nc, b = nt * nc;
    at Tr = 1 - (R0 + (1 - R0) * a);
    Tr) R = (D * nnt - N * (Dd
    E * diffuse;
    = true;
    refl + refr)) && (depth < MAXDEPTH)
    D, N );
    refl * E * diffuse;
    = true;
    MAXDEPTH)
    survive = SurvivalProbability( diffuse, i );
    estimation - doing it properly, closely following
    if;
    radiance = SampleLight( &rand, I, &L, &light );
    e.x + radiance.y + radiance.z ) > 0) && (radiance
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance
    random walk - done properly, closely following Section
    (survive)
    ;
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf );
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;

```

```

bool respawn = false;
for ( uint h = 0; h < HOLES; h++ )
{
    float dx = m_Hole[h]->x - m_Particle[i]->x;
    float dy = m_Hole[h]->y - m_Particle[i]->y;
    float sd = dx * dx + dy * dy;
    float dist = 1.0f / sqrtf( sd );
    dx *= dist, dy *= dist;
    float g = (250.0f * m_Hole[h]->g * m_Particle[i]->m) / sd;
    if ( g >= 1 ) { SpawnParticle( i ); break; respawn = true;
    m_Particle[i]->vx += 0.5f * g * dx; * !respawn;
    m_Particle[i]->vy += 0.5f * g * dy; * !respawn;
}
if ( respawn ) SpawnParticle( i );

```



Flow Control

Broken Streams

```

char a[4] = { 6, 7, 8, 9 };
char b[4] = { 20, 20, 20, 20 };
char c[4];
*(uint*)c = *(uint*)a + *(uint*)b;

```

Masked addition:

```

char a[4] = { 6, 7, 8, 9 };
char b[4] = { 20, 20, 20, 20 };
char mask[4] = { 255, 0, 255, 255 };
char c[4];
*(uint*)c = *(uint*)a + (*(uint*)mask & *(uint*)b);

```

```

char a[4] = { 6, 7, 8, 9 };
char b[4] = { 20, 20, 20, 20 };
uint mask4 = 0xFFFF00FF;
char c[4];
*(uint*)c = *(uint*)a + (*(uint*)b & mask4);

```



Flow Control

Broken Streams – Flow Divergence

Like other instructions, comparisons between vectors yield a *vector* of booleans.

```
__m128 mask = _mm_cmpeq_ps( v1, v2 );
```

The mask contains a bitfield: 32 x ‘1’ for each **TRUE**, 32 x ‘0’ for each **FALSE**.

The mask can be converted to a 4-bit integer using `_mm_movemask_ps`:

```
int result = _mm_movemask_ps( mask );
```

Now we can use regular conditionals:

```
if (result == 0) { /* false for all streams */ }
if (result == 15) { /* true for all streams */ }
if (result < 15) { /* not true for all streams */ }
if (result > 0) { /* not false for all streams */ }
```



Flow Control

Streams – Masking

More powerful than ‘any’, ‘all’ or ‘none’ via movemask is *masking*.

```
if (x >= 1 && x < PI) x = 0;
```

Translated to SSE:

```
__m128 mask1 = _mm_cmpge_ps( x4, ONE4 );
__m128 mask2 = _mm_cmplt_ps( x4, PI4 );
__m128 fullmask = _mm_and_ps( mask1, mask2 );
```

```
x4 = _mm_andnot_ps( fullmask, x4 );
```

(`_mm_andnot_ps` inverts the **first** argument.)



Flow Control

Streams – Masking

```

ics
& (depth < MAXDEPTH)
c = inside ? 1.0f : 0.0f;
nt = nt / nc; ddn = ddn * ddn;
ps2t = 1.0f - nnt * nnt;
D, N );
0);
at a = nt - nc, b = nt * nc;
at Tr = 1 - (R0 + (1 - R0) *
Tr) R = (D * nnt - N * (ddn
E * diffuse;
= true;
efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;
MAXDEPTH)
survive = SurvivalProbability( diffuse, i);
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light,
e.x + radiance.y + radiance.z) > 0) && (rand <
v = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance
random walk - done properly, closely following Section 3.1.2
ive)
;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf );
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;

```

```

float a[4] = { 1, -5, 3.14f, 0 };
if (a[0] < 0) a[0] = 999;
if (a[1] < 0) a[1] = 999;
if (a[2] < 0) a[2] = 999;
if (a[3] < 0) a[3] = 999;

```

in SSE:

```

__m128 a4 = _mm_set_ps( 1, -5, 3.14f, 0 );
__m128 nine4 = _mm_set_ps1( 999 );
__m128 zero4 = _mm_setzero_ps();
__m128 mask = _mm_cmplt_ps( a4, zero4 );

```



Flow Control

Streams – Masking

Take-away:

- In vectorized code, stream divergence is not possible.
- We solve this by keeping all lanes alive.
- ‘Inactive lanes’ use *masking* to nullify actions.

This approach is used in SSE/AVX, as well as on GPUs.

```

ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * nc;
        cos2t = 1.0f + nnt * ddn;
        D, N );
    }
    at a = nt - nc, b = nt + nc;
    at Tr = 1 - (R0 + (1 - R0) * a);
    Tr) R = (D * nnt - N * (ddn *
    E * diffuse;
    = true;
    -
    refl + refr)) && (depth < MAXDEPTH)
    D, N );
    refl * E * diffuse;
    = true;
    MAXDEPTH)
    survive = SurvivalProbability( diffuse );
    estimation - doing it properly, closely following
    if;
    radiance = SampleLight( &rand, I, &L, &light);
    e.x + radiance.y + radiance.z) > 0) && (abs(
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance
    random walk - done properly, closely following
    (survive)
    ;
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf);
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;

```



Flow Control

Streams – Masking

```

ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * ddn;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
}

at a = nt - nc, b = nt * nc;
at Tr = 1 - (R0 + (1 - R0) * a);
Tr) R = (D * nnt - N * (ddn * a + b));

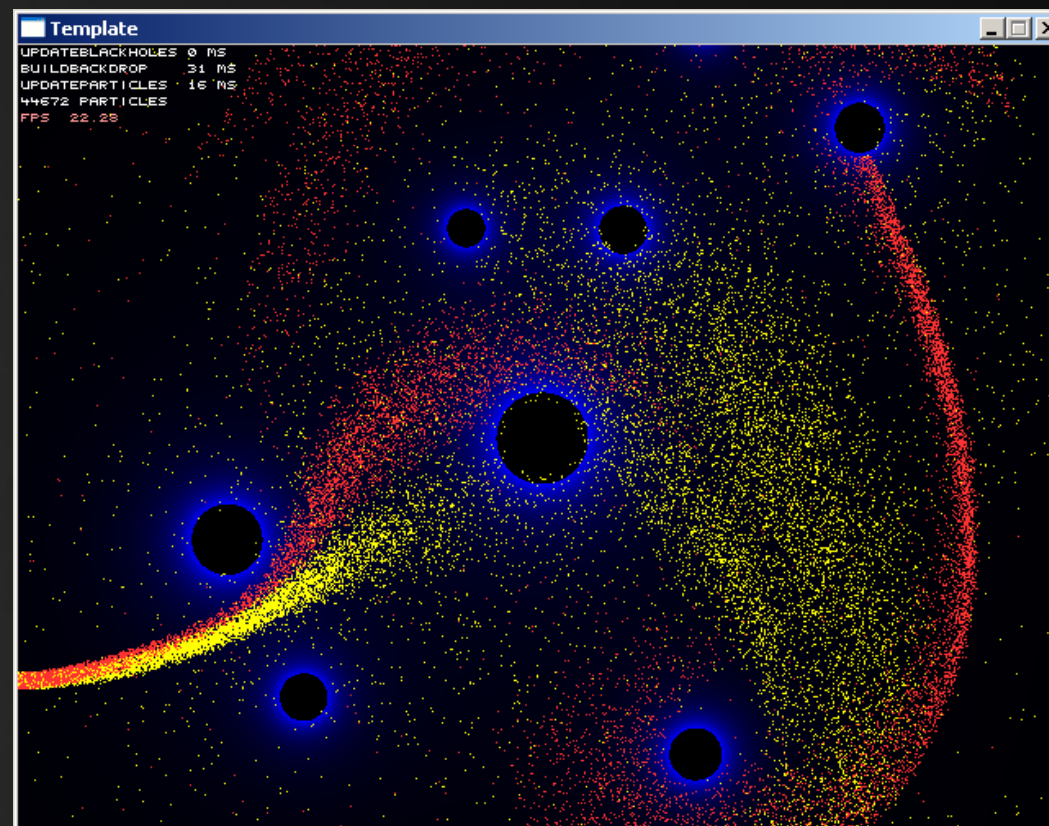
E * diffuse;
= true;

efl + refr)) && (depth < MAXDEPTH)
{
    D, N );
    refl * E * diffuse;
    = true;
}

MAXDEPTH)
{
    survive = SurvivalProbability( diffuse );
    estimation - doing it properly, closely following
    if;
    radiance = SampleLight( &rand, I, &L, &light );
    e.x + radiance.y + radiance.z) > 0) && (depth < MAXDEPTH)
    {
        w = true;
        at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
        at3 factor = diffuse * INVPI;
        at weight = Mis2( directPdf, brdfPdf );
        at cosThetaOut = dot( N, L );
        E * ((weight * cosThetaOut) / directPdf) * (radiance
    }

    random walk - done properly, closely following
    (survive)
}

at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf );
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
}
    
```



Flow Control

```

static union { float px[PARTICLES]; __m128 px4[PARTICLES / 4]; };
static union { float py[PARTICLES]; __m128 py4[PARTICLES / 4]; };
static union { float pvx[PARTICLES]; __m128 pvx4[PARTICLES / 4]; };
static union { float pvy[PARTICLES]; __m128 pvy4[PARTICLES / 4]; };
static union { float pm[PARTICLES]; __m128 pm4[PARTICLES / 4]; };
static bool pa[PARTICLES];
static union { uint pc[PARTICLES]; __m128i pc4[PARTICLES / 4]; };

```

...

```

// convert to SoA
for( int i = 0; i < PARTICLES; i++ )
{
    px[i] = m_Particle[i]->x;
    py[i] = m_Particle[i]->y;
    pvx[i] = m_Particle[i]->vx;
    pvy[i] = m_Particle[i]->vy;
    pa[i] = m_Particle[i]->alive;
    pc[i] = m_Particle[i]->c;
    pm[i] = m_Particle[i]->m;
}

```



Today's Agenda:

- Recap
- Flow Control
- AVX, Larrabee, GPGPU

```
ics
(depth < MAXDEPTH)
{
    if (inside) {
        nt = nt / nc; ddn = ddn / n;
        cos2t = 1.0f - nnt * nnt;
        D, N );
    }
    at a = nt - nc; b = nt + nc;
    at Tr = 1 - (R0 + (1 - R0) * r);
    Tr) R = (D * nnt - N * (ddn *
    E * diffuse;
    = true;
    refl + refr)) && (depth < MAXDEPTH)
    D, N );
    refl * E * diffuse;
    = true;
    MAXDEPTH)
    survive = SurvivalProbability( diffuse );
    estimation - doing it properly, closely following
    if;
    radiance = SampleLight( &rand, I, &L, &align);
    e.x + radiance.y + radiance.z) > 0) && (abs(
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance
    random walk - done properly, closely following
    survive)
    ;
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf );
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;
}
```

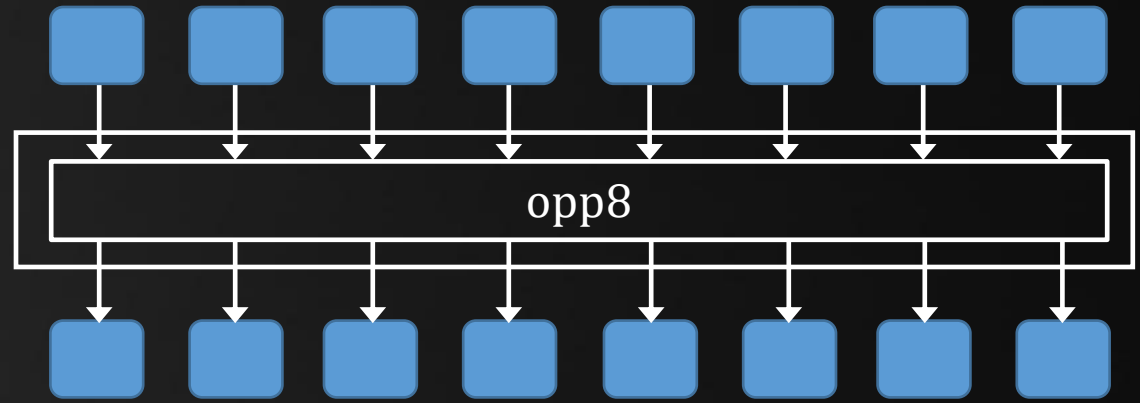
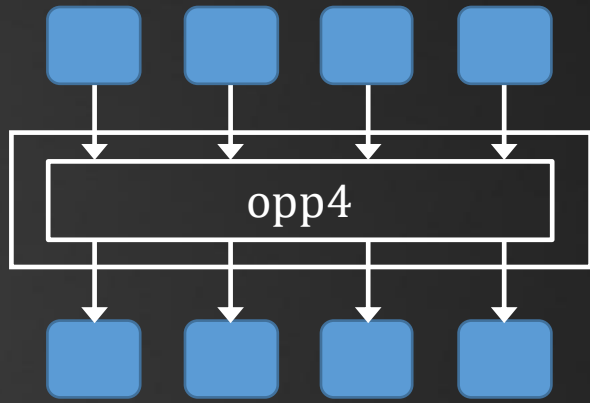


Beyond SSE

AVX*

```

ics
(depth < MAXDEPTH)
c = inside ? 1 : 0;
nt = nt / nc; ddn = ddn / ddn;
ps2t = 1.0f - nnt * nnt;
D, N );
);
at a = nt - nc, b = nt - nc;
at Tr = 1 - (R0 + (1 - R0) *
Tr) R = (D * nnt - N * (ddn
E * diffuse;
= true;
efl + refr) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;
MAXDEPTH)
survive = SurvivalProbability( diffuse,
estimation - doing it properly, closely
if;
radiance = SampleLight( &rand, I, &L, &light
e.x + radiance.y + radiance.z) > 0) && (rand
v = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance
random walk - done properly, closely following
ive)
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
    
```



`__m256`

`_mm256_add_ps`
`_mm256_sqrt_ps`
 ...etc.

*: On: ‘Sandy Bridge’ (Intel, 2011), ‘Bulldozer’ (AMD, 2011).



Beyond SSE

AVX2*

Extension to AVX: adds broader `_mm256i` support, and FMA:

$r8 = (a8 * b8) + c8$
`_mm256 r8 = _mm256_fmadd_ps(a8, b8, c8);`

Emulate on AVX: `r8 = _mm256_add_ps(_mm256_mul_ps(a8, b8), c8);`

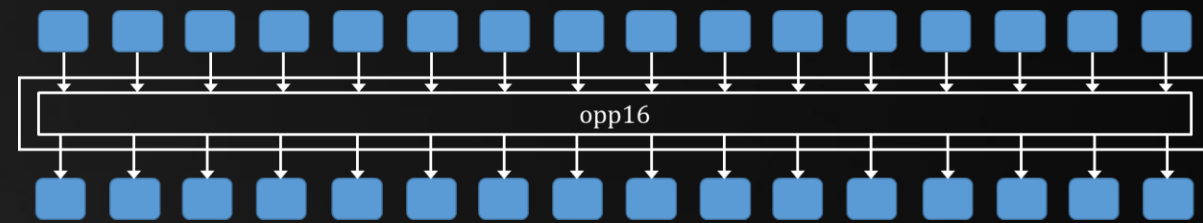
Benefits of *fused multiply and add*:

- Even more work done for a single ‘fetch-decode’
- Better precision: rounding doesn’t happen between multiply and add

*: On: ‘Haswell’ (Intel, 2013), ‘Carrizo’ and ‘Zen’ (AMD, 2015, 2017).



Beyond SSE



AVX512*

16-wide SIMD, with 32 512-bit registers (`__m512`, `__m512i`).

Most AVX512 instructions can be masked:

```
__m512 __mm512_maskz_add_ps( __mmask16 k, __m512 a, __m512 b )
```

“Add packed single-precision (32-bit) floating-point elements in a and b, and store the results in dst using zeromask k (elements are zeroed out when the corresponding mask bit is not set).”

For a full list of instructions, see:

<https://software.intel.com/sites/landingpage/IntrinsicsGuide>

*: On: ‘Skylake-X’ (Intel, 2013), ‘Carrizo’ and ‘Zen’ (AMD, 2015, 2017).

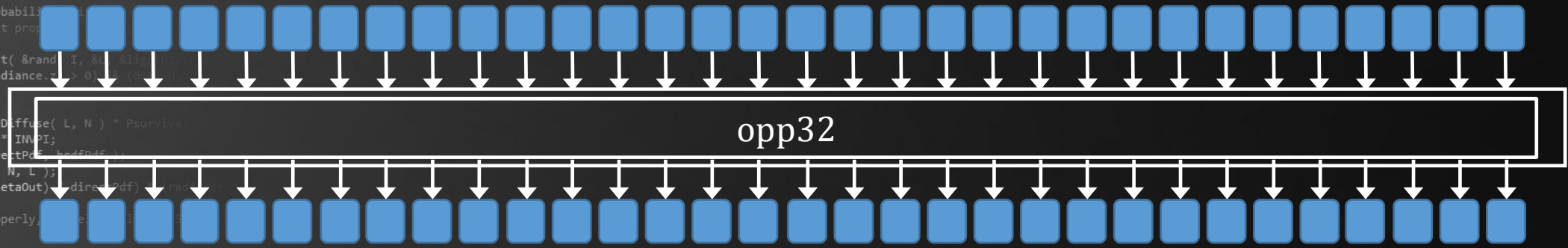


Beyond SSE

GPU Model

```

__kernel void main( write_only image2d_t outimg )
{
    int column = get_global_id( 0 );
    int line = get_global_id( 1 );
    float red = column / 800.;
    float green = line / 480.;
    float4 color = { red, green, 0, 1 };
    write_imagef( outimg, (int2)(column, line), color );
}
    
```



Beyond SSE

GPU Model

```

__kernel void main( write_only image2d_t outimg )
{
    int column = get_global_id( 0 );
    int line = get_global_id( 1 );
    float red, green, blue;
    if (column & 1)
    {
        red = column / 800.;
        green = line / 480.;
        color = { red, green, 0, 1 };
    }
    else
    {
        red = green = blue = 0;
    }
    write_imagef( outimg, (int2)(column, line), color );
}

```



Today's Agenda:

- Recap
- Flow Control
- AVX, Larrabee, GPGPU

```
ics
& (depth < MAXDEPTH)
{
    if ( ! inside )
    {
        nt = nt / nc; ddn = ddn * ddn;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
    at a = nt - nc; b = nt * nc;
    at Tr = 1 - (R0 + (1 - R0) *
    Tr) R = (D * nnt - N * (ddn *
    E * diffuse;
    = true;
    -
    refl + refr)) && (depth < MAXDEPTH)
    D, N );
    refl * E * diffuse;
    = true;
    MAXDEPTH)
    survive = SurvivalProbability( diffuse );
    estimation - doing it properly, closely following
    if;
    radiance = SampleLight( &rand, I, &L, &light;
    e.x + radiance.y + radiance.z) > 0) && (abs(
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance
    random walk - done properly, closely following
    survive)
    ;
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf;
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;
}
```



